



3D sensor for mobile applications

O3MXOOKG/CAN/E1/E3/AI/GM/97

Image sensor	PMD 3D ToF chip / 2D CMOS chip (HDR)	
Outputs		
Video output	Ethernet, RTP, RTSP, H.264, H.265, MJPEG (max. 1280 x 960)	
Monitoring range		
Image resolution	[px]	1280 x 960
Image resolution 3D	[px]	64 x 16
Angle of aperture	[°]	143 x 112
Angle of aperture 3D	[°]	97 x 44
Image repetition frequency	[Hz]	30
Image repetition frequency 3D	[Hz]	30
Software / programming		
Parameter setting options	via PC with ifm Vision Assistant	
Interfaces		
Communication interface	CAN; Ethernet	
Number of CAN interfaces	1	
Number of Ethernet interfaces	1	
CAN		
Transmission rate	250 (125...1000) kBaud	
Protocol	SAE J1939; UDS	
Factory settings	SAE J1939 interface: default device address (ECU): 239	
Usage type	Parameter setting; Data transmission	
Note on interfaces	Output of preprocessed data via CAN interface	
Ethernet		
Protocol	UDP/IP; TCP/IP	
Factory settings	3D IP address: 192.168.1.1 2D IP address: 192.168.1.3 subnet mask: 255.255.255.0 3D target IP address: 255.255.255.255 target port 42000	
Usage type	Data transmission; RTP/RTSP video stream (H.264, H.265, MJPEG)	
Note on interfaces	preprocessed data output and video output via Ethernet	
Operating conditions		
Ambient temperature	[°C]	-40...75
Storage temperature	[°C]	-40...90
Max. relative air humidity	[%]	90; (non condensing)
Max. height above sea level	[m]	4000
Protection	IP 67; IP 69K; (with mounted connectors or protective caps)	
Max. immunity to extraneous light	[klx]	120
Tests / approvals		
EMC	DIN EN 61000-6-4	industrial environments
	DIN EN 61000-6-2	industrial environments

O3M372



3D sensor for mobile applications

O3MXOOKG/CAN/E1/E3/AI/GM/97

Shock resistance	DIN EN 60068-2-27	30 g / 6 ms bump
Vibration resistance	DIN EN 60068-2-6	10 g / 10...500 Hz swept sine
	DIN EN 60068-2-64	10...1000 Hz noise
Electrical safety	DIN EN 61010-2-201	electric shock / electrical supply only via PELV circuits
MTTF [years]		47

Mechanical data

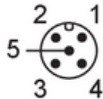
Weight [g]	1481.965
Dimensions [mm]	143.4 x 85 x 73.1
Material	housing: diecast aluminium; disc: gorilla glass

Remarks

Remarks	The illumination unit is required for the operation of the sensor. Only use original ifm cables to connect sensor and illumination unit. The function-specific performance values can be found in the applicable documentation.
Pack quantity	1 pcs.

Electrical connection - CAN

Connector: 1 x M12; coding: A



1	screen
2	9...32 V
3	GND
4	CAN-H
5	CAN-L

Electrical connection - Ethernet

Connector: 1 x M12; coding: D



1	TD +
2	RD +
3	TD -
4	RD -

Other data

Field of view size with lens distortion correction

Measuring range / distance [m]	Length [m]	Width [m]
5	11.3	4.0
10	22.6	8.1
15	33.9	12.1
30	67.8	24.2

O3M372



3D sensor for mobile applications

O3MXOOKG/CAN/E1/E3/AI/GM/97

measuring range for object recognition

object type / object size	application condition	Measuring range [m]
vehicle	sunny (~120 klx)	0.25...17
	cloudy (~20 klx)	0.25...25
	darkness	0.25...29
person	sunny (~120 klx)	0.25...7
	cloudy (~20 klx)	0.25...10
	darkness	0.25...12
retroreflector	sunny (~120 klx)	1...24
	cloudy (~20 klx)	1...35
	darkness	1...46
AI person detection		25
software variant:	OD object recognition	

measuring accuracy

application condition	measuring accuracy [cm]
	typical value
sunny (~120 klx)	± 15
cloudy (~20 klx)	± 10
darkness	± 5
software variant:	OD object recognition